

2D Scan Engine

MDI-3100-SR



MDI-3100-SR

This document provides specifications for the MDI-3100-SR imager scan engine.

Specifications Manual



All information subject to change without notice.

Document History

Model Number: MDI-3100-SR Specification Number: SS11056
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Revision History

Specification No. : SS11056 Product name : MDI-3100-SR

Edition	Date	Page	Section	Description of Changes
First	2012/06/28	-	-	Initial release
		5	6.1	Fixed interface signal Note
		16 11.2. 2012/01/24 18 16.1. 19 17.		EMC Specifications
2nd	2012/01/24			Fixed Packaging drawing
	2012/01/21			Fixed interface connector Correct :IRISO 9681-12 Wrong :HIROSE FH19C-12S
3rd	2015/09/18	16	12	RoHS; Fixed : 2002/95/EC ⇒ 2011/65/EU



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1. Abstract

This manual provides specifications for the MDI-3100-SR imager scan engine.

2. Overview

The MDI-3100-SR is an imager scan engine with an integrated decoder, which enables high speed scanning of standard linear (1D) and 2D symbologies. Main features of the MDI-3100-SR are as follows:

- · High-speed reading
 - Extremely high speed performance ensures stress free scanning and fast response without being affected by hand movement and light conditions.
- · Integrated decoder

The MDI-3100 with its combined camera and a decoder module offers ultra-miniature size. The compact design enables easy installation.

- Editing function
 - A new function "Data Editing Program" captures up to 16 codes on multiple images simultaneously in one go. Output editing process, such as GS1 format, also can be set easily.
- Low power consumption

Power consumption in operating, standby and low power states has been drastically reduced. Various power saving settings can be configured in low power mode.

- · LED aiming
 - A sharp single line of green LED makes it easy to aim the scanner while providing safety and long-life.
- RoHS compliance

The MDI-3100 is a RoHS compliant product, which is declared by Optoelectronics Co., Ltd.

Note: Refer to "Serial Interface / Software Specifications" for supported codes and commands.

3. Physical Features

3.1. Dimensions

Module : 25.3 × 21.0 × 12.4 (WDH mm)

3.2. Weight

Module : 8 grams (max)



4. Electrical Specifications

4.1. Absolute Maximum Ratings

Item	Symbol	Rated Value	Unit
Power Supply Voltage (V _{CC} to GND)	V _{CC}	-0.3 ~ 7.0	V
Input Voltage	Vı	-0.3 ~ V _{CC} +0.3	V

4.2. Electrical Characteristics

Item	Symbol	Conditions	Min.	Тур.	Max.	Unit
Operating Voltage (*1)	V_{CC}		3.0		5.5	V
Peak Rush Current (*2)	I _{PK}				2.5	Α

$$(V_{CC} = 3.3V, T_A = 25^{\circ}C)$$

Item	Symbol	Conditions	Min.	Тур.	Max.	Unit
DVD CTC	V _{IH}		2			V
RxD, CTS	V_{IL}				0.8	V
AIM, WAKEn	V _{IH}		2			V
DWNLDn, TRIGn	V _{IL}				0.2 _X V _{CC}	V
POWERDWN	V_{OH}		100K toVCC			V
POWERDWIN	V _{OL}	(I _O = 1.5mA)			0.4	V
DUZZEDa CD LEDa	V_{OH}		100K toVCC			V
BUZZERn, GR_LEDn	V_{OL}	(I _O = 16mA)			0.55	V
TxD, RTS	V _{OH}	(I _O = -6mA)	10K toVCC			V
IXD, NIO	V_{OL}	(I _O = 6mA)			0.55	V

$$(V_{CC} = 5.0V, T_A = 25^{\circ}C)$$

Item	Symbol	Conditions	Min.	Тур.	Max.	Unit
RxD, CTS	V _{IH}		0.7 x V _{CC}			V
RXD, C13	V _{IL}				$0.3 \times V_{CC}$	V
AIM, WAKEn	V _{IH}		2			V
DWNLDn, TRIGn	V _{IL}				$0.2 \times V_{CC}$	V
POWERDWN	V _{OH}		100K toVCC			V
FOWERDWIN	V _{OL}	(I _O = 4mA)			0.4	V
BUZZERn, GR LEDn	V _{OH}		100K toVCC			V
BUZZEKII, GK_LEDII	V _{OL}	(I _O =16mA)			0.55	V
TxD, RTS	V _{OH}	(I _O =-12mA)	10K toV _{CC}			V
IXD, KIS	V _{OL}	(I _O =12mA)			0.55	V

^{*1} Input connector portion

^{*2} V_{CC} is supplied by a direct-current power supply of 2 A and measurement is done using a current probe.



4.3. Current Consumption in Default Setting

 $(V_{CC} = 3.3V, T_A = 25^{\circ}C)$

					•		
Item	State	Symbol	Conditions	Min.	Тур.	Max.	Unit
Operating Current	Read	I _{OP}	-	-	240	390	mA
Standby current (*1)	Standby	I _{STB}	-	-	45	50	mA
Deep standby mode current (*2)	Stariuby	I _{DSP}	Configured	-	27	30	mA
Sleep mode current (*3)	Low	I _{SLP}	Configured	-	0.25	0.3	mA
Power off mode current (*4)	Power	I _{PWO}	Configured	ı	0.02	0.03	mA

 $(V_{CC} = 5.0V, T_A = 25^{\circ}C)$

Item	State	Symbol	Conditions	Min.	Тур.	Max.	Unit
Operating Current	Read	I _{OP}	-	ı	160	260	mA
Standby current (*1)	Standby	I _{STB}	-	ı	35	40	mA
Deep standby mode current (*2)	Stariuby	I _{DSP}	Configured	-	25	28	mA
Sleep mode current (*3)	Low	I _{SLP}	Configured	-	0.22	0.27	mA
Power off mode current (*4)	Power	I _{PWO}	Configured	-	0.04	0.05	mA

^{*1} Current except the baud rate 115200 bps.

4.4. **Recovery Time from Low Power and Power Down States**

Item	State	Conditions	Min	Тур	Max	Unit
Sleep Mode	Low Dower	Configured	-	75	100	ms
Power Off Mode	Low Power	Configured	-	550	700	ms
Power ON	Power Down	-	-	550	700	ms

Note: Refer to "Serial Interface / Software Specifications" for details.

^{*2} When set to Deep Standby mode by a command. In Deep Standby mode, command control conditions differ from the normal Standby mode. Besides that, there is no difference from the normal Standby mode.

^{*3} When set to Sleep mode by a command

^{*4} When set to Power Off by a commend

^{*3*4} In Low Power mode, Sleep or Power Off modes are configurable

* Refer to "Serial Interface / Software Specifications" for details

Refer to "Serial Interface / Software Specifications" for details.



5. Power Mode Transition

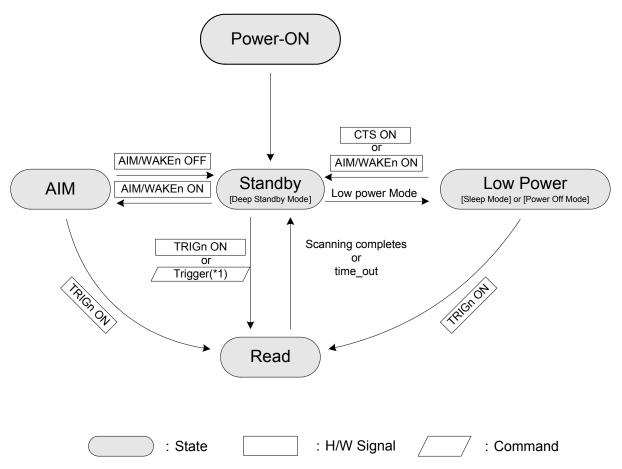


Figure 1: Power Mode Transition

- *1 When Deep Standby mode is set, there are control conditions for command transmission.
- * When Low Power state is enabled, the MDI-3100 automatically enters Low Power state after Power On.
- * In Low Power state, Sleep mode or Power Off mode is configurable.
- * When Low Power state is enabled, the MDI-3100 is in Standby state, and there are no events to move to other states, the MDI-3100 goes to Low Power state after the time out period specified by power saving command has elapsed.
- * Refer to "Serial Interface / Software Specifications" for details.



6. Interface Specifications

6.1. Interface Signals

Connector used is equivalent to the one produced by IRISO Electronics Co., Ltd. Product No.: 9681-12 (12pin) (Bottom contact)

No.	Name	Function	I/O	State	Note
1	TRIGn	Trigger on	In	L: Start operation H: No action	(100kΩ pull up on module)
2	AIM/WAKEn	Recovery signal from Low Power state	In	L: Recover from Low Power state H: No action	(100kO mill un on modulo)
2	AllW/WAREII	Aiming control signal in other states than Low Power	In	L: Aiming LED on H: Aiming LED off	. (100kΩ pull up on module)
3	GR_LEDn	Good read LED signal	Out	L: LED on H: LED off	(100kΩ pull up on module)
4	BUZERn	Activate external buzzer signal	Out	L: Active H: No action	Possible to change tones and sound pressure by sending PWM signals. (100kΩ pull up on module)
5	POWERDWN	Shows Low Power state	Out	L: Normal state H: Low Power state	(100kΩ pull up on module)
6	RTS	Communication control signal to host system	Out		(10KΩ pull up on module)
7	CTS	Communication control signal from host system	In		(100kΩ pull up on module)
8	TxD	Transmitted data signal	Out		(10kΩ pull up on module)
9	RxD	Received data signal	In		(100kΩ pull up on module)
10	GND	System ground			
11	Vcc	Power input	In	3.0 ~ 5.5V	
12	DWNLDn	Forced download control signal	In	L: Forced Download mode H: Normal state	Check the signal when the power is supplied and enable rewriting software. (100kΩ pull up on module)

Note: Refer to "Serial Interface / Software Specifications" for UART communication timing.



7. Optical Specifications

Basic Optical Specifications

	Item	Characteristics
Scan method	CMOS area sensor (black and white)	-
Number of effective pixel	(H) × (V)	752 × 480 dot
Image capture speed (*1)	Frame rate	60 fps
Focal distance	From the front edge of scan engine	130 mm
View angle	Horizontal	Approx. 40.6°
view arigie	Vertical	Approx. 26.4°
	Red LED	-
Auxiliary light source	Peak Wave Length	617 nm
(LED × 2)	Directivity angle 2θ1/2 (*2)	60°
	Maximum radiation output (*3)	15000 mcd
	Green LED	-
Light source for aiming (LED x 1)	Peak Wave Length	528 nm
(^ .)	Maximum radiation output (*4)	18700 mcd

^{*1} The fastest seed of image capture*2 The reference value extracted from the LED datasheet

^{*3 *4} The reference value extracted from the datasheet (conditions: 25 °C, IF = 140 mA)



7.2. Aiming Pattern

The aiming is used for the following purpose:

- 1. Fill light to recognize the appropriate reading range.
- 2. Fill light when auto trigger is used.

The aiming specifications are as follows:

- An optical axis of imaging field of view and the center of horizontal aiming width coincide at a distance of L=110±20 mm from the front edge of the camera module.
- The aiming horizontal width to the horizontal width of imaging filed of view at a distance of L=110 is 80%±10%.

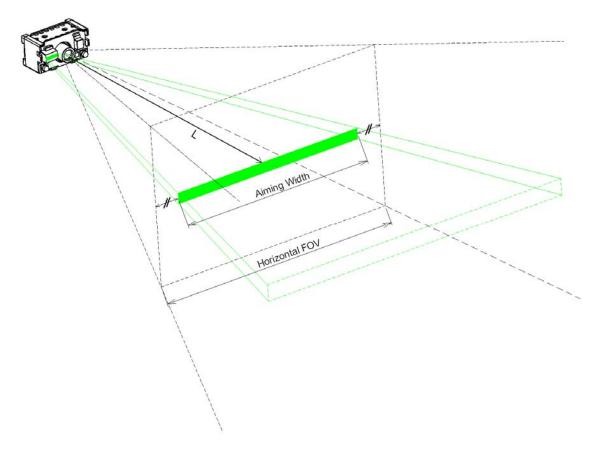


Figure 2: Aiming Pattern



8. Technical Specifications

Emit aiming light of the MDI-3100-SR to the center of a bar code for scanning. The conditions for technical specifications are as follows, unless otherwise specified in each section.

<Conditions>

Ambient Temperature and Humidity : Room temperature and room humidity Ambient Light : 100 ~200 lux (on the surface of a bar code)

Pitch Angle: α = 0°Skew Angle: β = 15°Tilt Angle: γ = 0°Curvature: R = ∞

Power Supply Voltage : 3.3 and 5.0 V PCS (1D and 2D) : 0.9 or higher

Scanning Test : Accept the performance with 90% or more success

rate for 10 tries of scan. One scan should be tested

within 2 seconds.

Bar Code Test Sample (1D and 2D) : Specified below

< Test chart >

For 1D codes, OPTOELECTRONICS test samples

For GS1 Databar, stacked codes and 2D codes, printed by a dedicated printer for bar code



8.1. Bar Code Test Sample

1 D Bar Codes

<Code 39>

Resolution	Symbology	PCS	Size (mm)	No. of Digits
0.127 mm (5mil)			32 × 10	15
0.20 mm (7.9mil)	Code 39	0.0	100 × 10	31
0.254 mm (10mil)	Code 39	0.9	32.5 × 10	7
0.508 mm (20mil)			36 × 25	4

<Code 128>

Resolution	Symbology	PCS	Size (mm)	No. of Digits
0.20 mm (7.9mil)	Code 128	0.9	42 × 10	16

<UPC>

Resolution	Symbology	PCS	Size (mm)	No. of Digits
0.330 mm (13mil)	12-digit UPC	0.9/0.3	31.5 × 25.0	12

<Codabar>

Resolution	Symbology	PCS	Size (mm)	No. of Digits
0.15 mm (6mil)	Codabar	0.9	20 × 10	10

GS1 Databar

<GS1-limited>

Resolution	Symbology	PCS	Size (mm)	No. of Digits
0.169 mm (6.7mil)	Limited	0.9	12 × 1.5	14
0.169 mm (6.7mil)	Limited-Composite	0.9	12 × 3.0	26

2 D Codes

<PDF417>

Resolution	Error Correction	PCS	Size (mm)	No. of Character
0.169 mm (6.7mil)	Level-3	0.9	23 × 10	- 58
0.254 mm (10mil)			35 × 15	

<QR Code: Model-2>

Resolution	Error Correction	PCS	Size (mm)	No. of Character
0.212 mm (8.4mil)	М	0.9	6 × 6	44
0.381 mm (15mil)			11 × 11	

<Data Matrix>

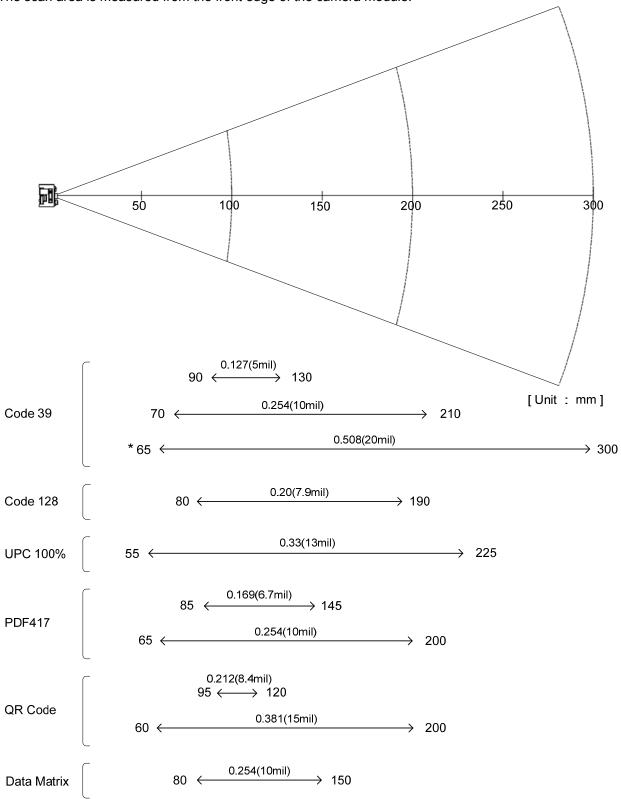
Resolution	Model	PCS	Size (mm)	No. of Character
0.212 mm (8.4mil)	ECC200	0.9	5 × 5	40
0.254 mm (10mil)			6 × 6	

Note: The size is outline dimensions excluding quiet zone.



8.2. Scan Area and Depth of Field

The scan area is measured from the front edge of the camera module.



Note: The depth of field depends on the view angle and symbol length

Figure 3: Scan Area and Depth of Field



8.3. Print Contrast Signal

PSC 0.3 or higher

<Conditions>

MRD : 32% and higher

(70% or higher reflectivity of space and quiet zone)

Distance : 130 mm from the front edge of the camera module

Bar Code Sample : UPC specified in Chapter 8. (Resolution: 0.33 mm, PCS: 0.3)

MRD = Minimum reflectance of white bar - Maximum reflectance of black bar

Reflectance of white bar—Reflectance of black bar

Reflectance of white bar

8.4. Minimum Resolution

1D Code : 0.127 mm (5 mil) Code 39 specified in Chapter 8

GS1-Databar : 0.169 mm (6.7 mil) GS1 Databar-Limited specified in Chapter 8

Stacked Code : 0.169 mm (6.7 mil) PDF417, GS1 Databar-Limited Composite specified in Chapter 8

2D Code : 0.212 mm (8.4 mil) OR Code and Data Matrix specified in Chapter 8

<Conditions>

Bar Code Sample : The above codes specified in Chapter 8

Distance : 100 mm from the front edge of the camera module

Angle : $\alpha = 0^{\circ}$, $\beta = +15^{\circ}$, $\gamma = 0^{\circ}$

Curvature : R = ∞

For the pitch angle and tilt angle measurement, set the skew angle β = +15°

8.5. Wide Bar Code

Code 39 with width of 100 mm and resolution of 0.2 mm can be read.

<Conditions>

Bar Code Sample : 0.20 mm Code 39 specified in Chapter 8

Distance : 160 mm from the front edge of the camera module

Angle : $\alpha = 0^{\circ}$, $\beta = +15^{\circ}$, $\gamma = 0^{\circ}$

Curvature : R = ∞

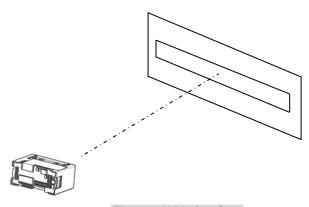


Figure 4: Wide Bar Code



8.6. Motion Tolerance

UPC bar code 100% can be read when it is moving at 2m/s.

<Conditions>

Ambient Temperature and Humidity : Room temperature and Room humidity

Ambient Light : 500 lux to 1000 lux (on the surface of a bar code)
Distance : 130 mm from the front edge of the camera module

 $\begin{array}{lll} \text{Angles} & : \alpha = 0^{\circ} \\ \text{Skew} & : \beta = 15^{\circ} \\ \text{Tilt} & : \gamma = 0^{\circ} \\ \text{Curvature} & : R = \infty \end{array}$

Power Supply Voltage : 3.3 and 5.0 V PCS (1D and 2D) : 0.9 or higher

Bar Code Sample : UPC with 0.33 mm resolution specified in Chapter 8

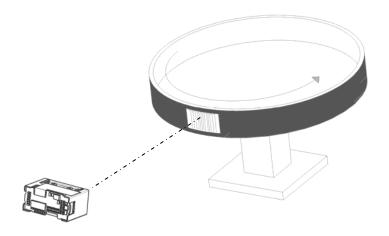


Figure 5: Motion Tolerance

Note: The above shows the possible speed of reading, but no guarantee of 100% reading.

: Scanning may fail due to the specular reflection of illumination LEDs when the reflectivity is high.



8.7. Pitch, Skew, and Tilt

Pitch : $\alpha = \pm 50^{\circ}$ Skew : $\beta = \pm 50^{\circ}$ Tilt : $\gamma = \pm 180^{\circ}$

<Conditions>

Bar Code Sample : 0.33 mm UPC specified in Chapter 8

Distance : 130 mm from the front edge of the camera module

Curvature : R = ∞

For the pitch angle and tilt angle measurement, set the skew angle β = +15°

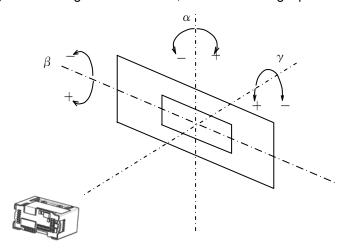


Figure 6: Pitch, Skew, and Tilt

8.8. Curvature

0.33 mm 12-digit UPC : $R \ge 20$ mm 0.15 mm 10-digit Codabar : $R \ge 16$ mm

<Conditions>

Bar Code Sample : 0.33 mm UPC specified in Chapter 8

Distance : 110 mm from the front edge of the camera module

Angle : $\alpha = 0^{\circ}$, $\beta = +15^{\circ}$, $\gamma = 0^{\circ}$

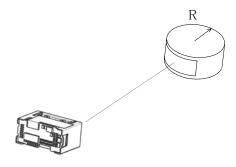


Figure 7: Curvature

Note: Scanning may fail due to the specular reflection of illumination LEDs when the reflectivity is high.



9. Environmental Specifications

9.1. Temperature

Operating Temperature : -30 to 60 °C Storage Temperature : -40 to 70 °C

<Conditions>

Bar Code Sample : 0.33 mm UPC specified in Chapter 8

Distance : 130 mm from the front edge of the camera module

Angle : $\alpha = 0^{\circ}$, $\beta = +15^{\circ}$, $\gamma = 0^{\circ}$

Curvature : R = ∞

Scanning Test : Read at intervals of 300 ms

Power Supply Voltage : 3.3 and 5.0 V

9.2. Humidity

Operating Humidity : 5 to 90% RH (no condensation, no frost) Storage Humidity : 5 to 90% RH (no condensation, no frost)

<Conditions>

Bar Code Sample : 0.33 mm UPC specified in Chapter 8

Distance : 130 mm from the front edge of the camera module

Angle : $\alpha = 0^{\circ}$, $\beta = +15^{\circ}$, $\gamma = 0^{\circ}$

Curvature : R = ∞

Power Supply Voltage : 3.3 and 5.0 V

9.3. Ambient Light Immunity

Scanning performance is guaranteed when the illuminance on a bar code surface is between zero and the following values:

Incandescent Light : 10,000 lux Fluorescent Light : 10,000 lux Sunlight : 100,000 lux

<Conditions>

Bar Code Sample : 0.33 mm UPC specified in Chapter 8

Distance : 130 mm from the front edge of the camera module

Angle : $\alpha = 0^{\circ}$, $\beta = +15^{\circ}$, $\gamma = 0^{\circ}$

Curvature : R = ∞

Power Supply Voltage : 3.3 and 5.0 V

Note: Scanning performance is guaranteed as far as the direct ambient light or specular reflection from the illumination LED does not enter the light receiving section of the MDI-3100.



9.4. Electrical Noise

(a) Scanning Symbologies

There shall be no abnormalities in the output signals when sinusoidal electrical noise (50 Hz to 100 kHz, smaller than 0.1 Vp-p) is added to the power supply line.

<Conditions>

Scan Method : Continuous scanning

Bar Code Sample : 0.33 mm UPC specified in Chapter 8

Distance : 130 mm from the front edge of the camera module

Angle : $\alpha = 0^{\circ}$, $\beta = +15^{\circ}$, $\gamma = 0^{\circ}$

Curvature : R = ∞

Scanning Test : Read at intervals of 300 ms

Power Supply Voltage : 3.3 and 5.0V

(b) Image Data Acquisition

There shall be no excessive noise or misalignments in acquired images when sinusoidal electrical noise (50 Hz to 100 kHz, smaller than 20 mVp-p) is added to the power supply line.

Note: There may be a case where the electrical noise affects the quality of captured images. The signal processing system of the MDI-3100 is especially designed for the purpose of scanning symbologies but not for the acquisition of image data. Therefore, the quality of captured images of the MDI-3100 may be lower than that of general digital cameras.

9.5. Vibration Strength

There shall be no sign of malfunction of the MDI-3100 after the following vibration test.

<u>Vibration Test:</u> Increase the frequency of the vibration from 12Hz to 200Hz at accelerated velocity 32.3m/S²(3.3G) for ten minutes. Continue this routine for 2 hours to X-direction, 2 hours to Y-direction and 4 hours to Z-direction.

<Conditions>

Bar Code Sample : 0.33 mm UPC specified in Chapter 8

Distance : 130 mm from the front edge of the camera module

Angle : $\alpha = 0^{\circ}$, $\beta = +15^{\circ}$, $\gamma = 0^{\circ}$

Curvature : R = ∞

Power Supply Voltage : 3.3 and 5.0 V

9.6. Drop Impact Strength

There shall be no sign of malfunction of the MDI-3100 after the following shock test. **Drop test:** Fix the MDI-3100 in a specific dummy case and drop it 10 times in total, at top, bottom, front, back, left, right, top-left, top-right, bottom-left and bottom-right faces, from a height of 180 cm onto a concrete floor.

<Conditions>

Bar Code Sample : 0.33 mm UPC specified in Chapter 8

Distance : 130 mm from the front edge of the camera module

Angle : $\alpha = 0^{\circ}$, $\beta = +15^{\circ}$, $\gamma = 0^{\circ}$

Curvature : R = ∞

Power Supply Voltage : 3.3 and 5.0 V



10. Integration Specifications

Connection between the decoder board and a host system:

Use a cable developed in accordance with specifications provided by a connector manufacturer to connect the MDI-3100 with the host system.

Connector used is produced by IRISO Electronics Co., Ltd.

Product No. : 9681-12 (12pin) Cable Length : 50 mm (max)

Note: Refer to "Integration Guide" for details.

11. Regulatory Specifications

11.1. LED Safety

Lamp classification: IEC62471:2006 Exempt Group

11.2. EMC

EN 55022:2006+A1:2007 (Class B) FCC Part 15, Subpart B (Class B)

12. RoHS

The MDI-3100 is compliant with RoHS.

Note: RoHS: The restriction of the use of certain hazardous substances in electrical and electronic equipment, 2011/65/EU.

13. Reliabilities

MTBF 53310 hours

Note: The reliability of the MDI-3100 is guaranteed as far as it is operated under normal operating conditions in the range of advised operating temperature and without excessive electrical or mechanical shock.

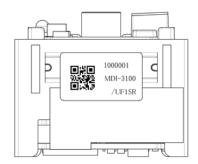
14. Precautions

- All work-benches, tools, measuring instruments and any part of human body which have come
 into contact with the MDI-3100 must undergo preliminary antistatic treatments.
- Do not touch the optical and electrical components. Hold it on the chassis when carrying the MDI-3100.
- Avoid handling the MDI-3100 in a dusty area. In case dust gets on the MDI-3100, gently blow it off
 with dry air. Direct contact of swabs and such on its optical part may cause deterioration of its
 performance.
- Do not drop the MDI-3100.



15. Serial Label

The serial label is affixed to the MDI-3100 as shown below.



The details of the label are as follows.

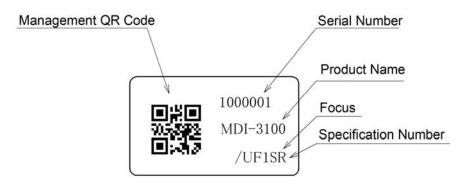


Figure 9: Serial label

The serial number (seven-digit) starts from 1000001 and is sequentially numbered regardless of lot number.

Note: SR stands for Standard Range Focus. : HD stands for High Density Focus.



16. Packaging Specifications

16.1. Packaging

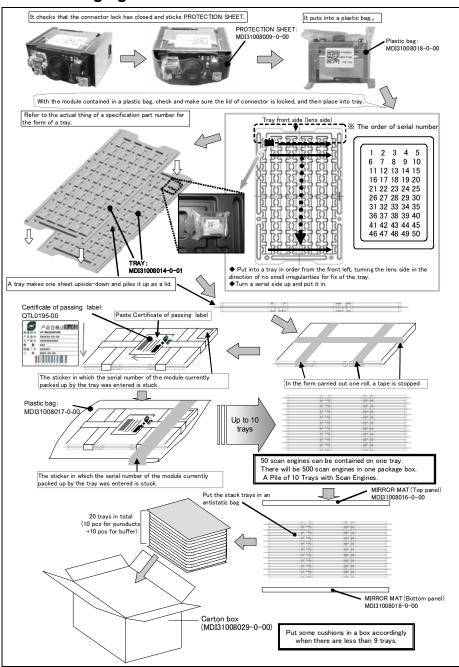


Figure 8: Packaging

Product name, number of products contained within and name of the manufacturer shall be displayed on the packing box.

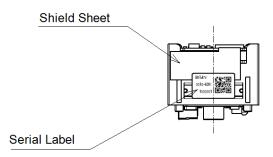
16.2. Package Size

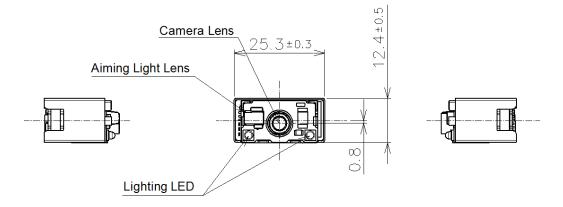
 $405 \times 260 \times 211$ (WDH mm) (Inside dimension)

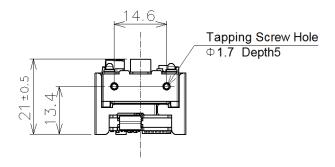
Note: 'Ro mark' on the trays and the boxes for the product indicates that the product is RoHS compliant, which is declared by Optoelectronics Co., Ltd.

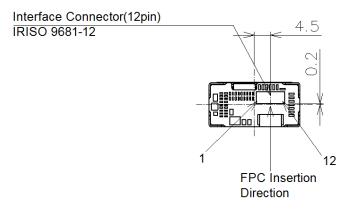


17. Mechanical Drawing









Note: The depth of the HD model is $0.2\,\mathrm{mm}$ deeper in size than that of the SR model.

Figure 10: Camera Module